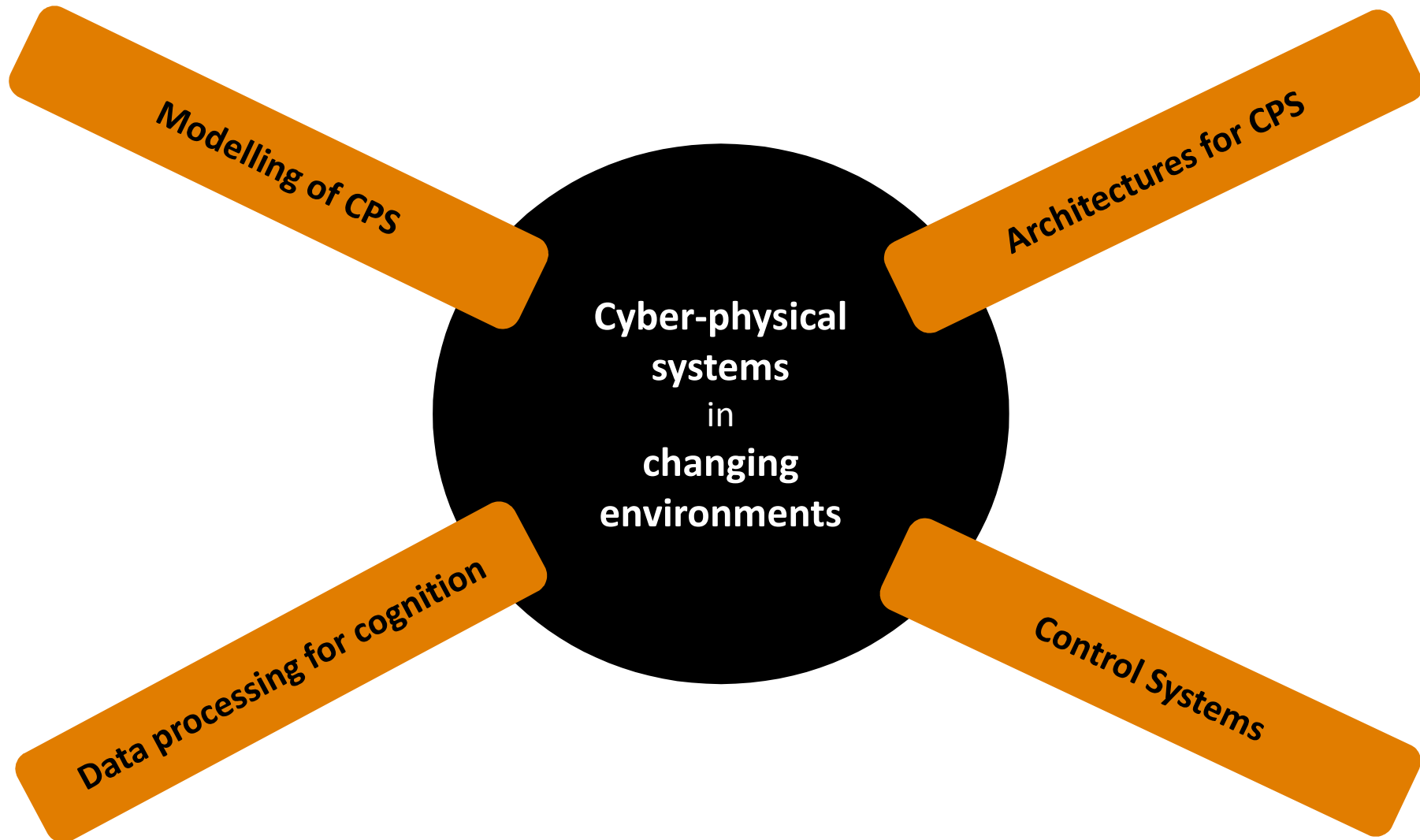


Research Laboratory for Proactive Technologies Department of Computer Control TUT

Jürgo-Sören Preden
Research Laboratory for Proactive Technologies
Department of Computer Control
Tallinn University of Technology



Jürgo Preden 2015



Pervasive computing

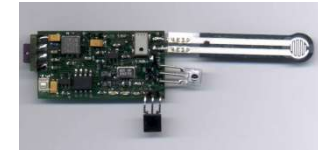
Cyber Physical Systems

- Also *ubiquitous, invisible computing*
- Devices and systems work in the environment
 - Invisible to the human
 - Without the aid of a human



Technologies

- Sensing and sensors



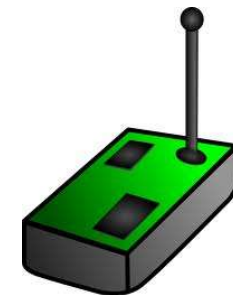
- Various modalities (temperature to visual)
- Signal processing to detect situations of interest

- Communication in distributed sensing and control applications



- Machine cognition and situational awareness in SoS

- RFID, sensor networks – tagging and monitoring objects

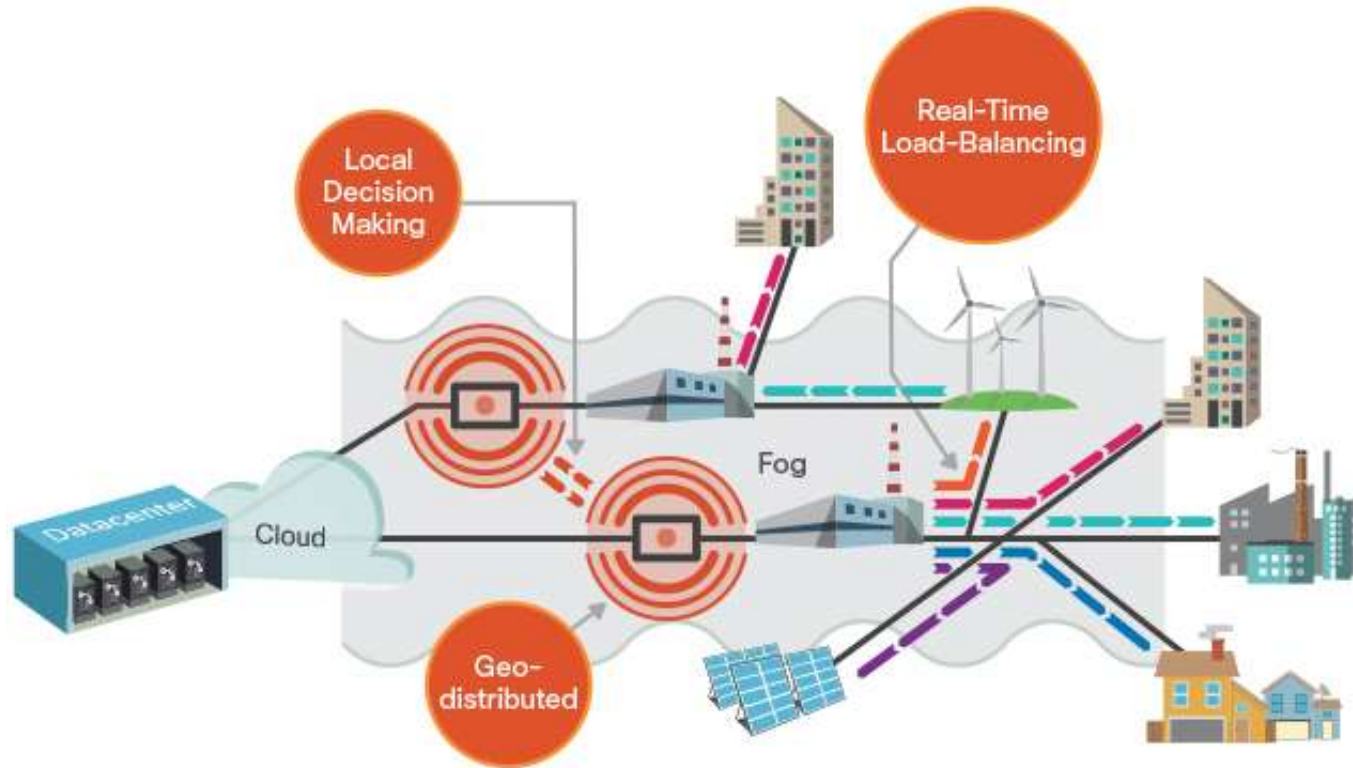


Smart networks

- Sensing and computation occurs in the network
 - Signal processing
 - Local decision making
- ProWare – proactive middleware enables collaboration of embedded devices
- Simple devices can become smart and work together
 - Street light can talk to a movement sensor

Mist / Fog computing

Internet of Things

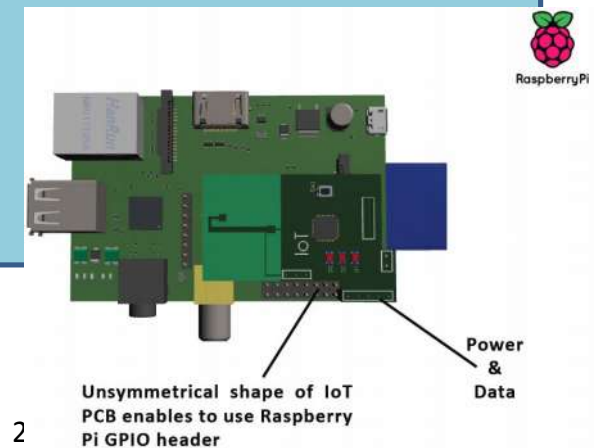
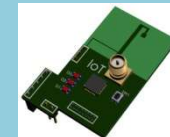


Technology Radar Trends | Fog Computing

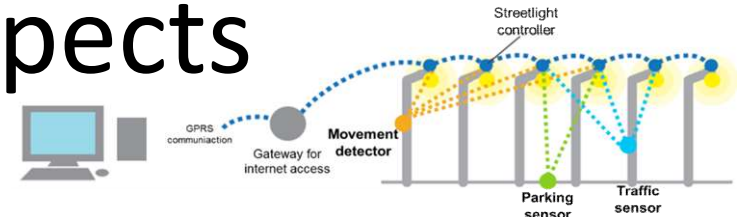
Moving computing from the Cloud to the edge of the network

Internet of Things applications

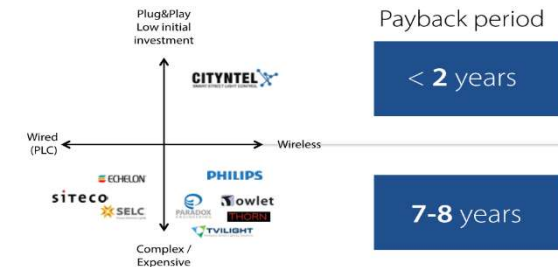
- with Thinnect (Estonian SME)
 - Mist computing applications, e.g., building information management
- with Cityntel (Estonian SME)
 - Smart street light control product, operational in 5 countries
- IoT module
 - Contains ProWare & IoT mesh
 - Raspberry Pi
 - Arduino



Commercial aspects



- We offer & develop state of the art technology
- First solutions are operational in 5 countries
- We have a strong value proposition to our partners
- We work with industry leaders



Supervisors

- Jürigo Preden, senior researcher
- Andri Riid, senior researcher
- Erki Suurjaak, engineer
- Johannes Ehala, PhD student
- Jaanus Kaugerand , PhD student
- Sergei Astapov, PhD student
- Raido Pahtma, PhD student
- Timo Tomson, PhD student



Thesis topics (WSN)

- Location aware WSN node
 - Wireless sensor network node with GPS
 - Dynamically deployed WSN node determines its locations and operates based on location
- Cross standard WSN node
 - Wireless sensor node with Bluetooth LE and 802.15.4 interface (based on CC2650)
- Smartphone interface to WSN
 - 802.15.4 bridge with Nordic NRF52
- WSN node performance comparison
 - Run various real-world algorithms on real WSN nodes

Thesis topics (signal processing)

- Source separation techniques
 - Separating several signal sources from a single signal (separating 2-3 acoustic, vibration, ECG signals) in Matlab
- Acoustic signal de-noising using multiple microphones
 - concentrating on a specific sound source position and attenuating the sounds from other sources and ambient noise in Matlab
- Fitness metrics in multidimensional cluster analysis
 - study and/or propose own metrics for clustering in order to increase clustering quality
- Optimal color space for recognition of given object

Thesis topics (robotics)

- Self aware robotic car
 - A robotic car, which follows an object emitting a certain sound
- Pattern (face) recognition from images
 - Recognizing a specific pattern (e.g. face) from an image using an off the shelf library like Open CV (Android)
- Live object tracking
 - Tracking a user-selected object in a vide feed (Android)
- Fridge camera system
 - Camera system for reconigzing contents of a refrigerator

Thesis topics (networking)

- Distributed Tracking Using Ultrasonic Sensor Grid
 - distributed sensor grid using autonomous wireless ultrasonic sensor systems to determine the position and vector of a mobile object
- Modelling Emergent Behaviour Using Multiagent System
 - implement a distributed multiagent system consisting of heterogeneous cyberphysical systems (e.g. Raspberry Pi)
- Establishing a Local Grid for Wireless Sensor Network Nodes
 - sensor nodes become aware of other sensors' relative positions, creating spatial situational awareness (for data fusion)

Thesis topics (various)

- Sub-millisecond time synchronization with COTS HW on local network
 - Time synchronization on COTS embedded hardware Raspberry Pi or BeagleBone Black
- Non-linear controller for swing type pendulum
 - Balancing a swing with dynamically moving masses
- Applying a seismic sensor
 - Evaluation of the properties of a COTS seismic sensor in a real-world applications
- Smart Indoor Lighting & Building Information Management Solution
 - Solution for smart control of indoor lighting

Thesis topics (Situation Awareness)

- Situational information exchange application
 - Application for exchanging situational information between people using a GIS interface

ProLab thesis topics:

<https://goo.gl/MBDucq>



Control Lab
www.a-lab.ee



TALLINN UNIVERSITY OF
TECHNOLOGY

Lõputööde teemad (automaatjuhtimise suund)

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19. veebruar 2015 a.

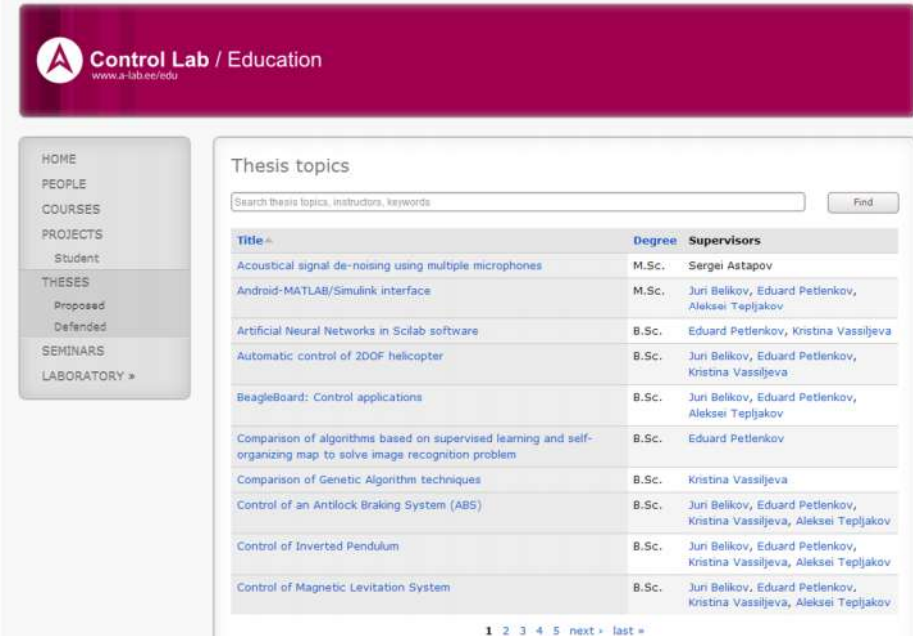


Euroopa Liit
Euroopa
Regionaalarengu Fond



Eesti tuleviku heaks

Lõputööde teemad



The screenshot shows the 'Thesis topics' page on the Control Lab / Education website. The page features a search bar and a table of thesis topics. The table has three columns: Title, Degree, and Supervisors. The topics listed include 'Acoustical signal de-noising using multiple microphones', 'Android-MATLAB/Simulink interface', 'Artificial Neural Networks in Scilab software', 'Automatic control of 2DOF helicopter', 'BeagleBoard: Control applications', 'Comparison of algorithms based on supervised learning and self-organizing map to solve image recognition problem', 'Comparison of Genetic Algorithm techniques', 'Control of an Antilock Braking System (ABS)', 'Control of Inverted Pendulum', and 'Control of Magnetic Levitation System'.

Title	Degree	Supervisors
Acoustical signal de-noising using multiple microphones	M.Sc.	Sergei Astapov
Android-MATLAB/Simulink interface	M.Sc.	Juri Belikov, Eduard Petlenkov, Aleksei Tepljakov
Artificial Neural Networks in Scilab software	B.Sc.	Eduard Petlenkov, Kristina Vassiljeva
Automatic control of 2DOF helicopter	B.Sc.	Juri Belikov, Eduard Petlenkov, Kristina Vassiljeva
BeagleBoard: Control applications	B.Sc.	Juri Belikov, Eduard Petlenkov, Aleksei Tepljakov
Comparison of algorithms based on supervised learning and self-organizing map to solve image recognition problem	B.Sc.	Eduard Petlenkov
Comparison of Genetic Algorithm techniques	B.Sc.	Kristina Vassiljeva
Control of an Antilock Braking System (ABS)	B.Sc.	Juri Belikov, Eduard Petlenkov, Kristina Vassiljeva, Aleksei Tepljakov
Control of Inverted Pendulum	B.Sc.	Juri Belikov, Eduard Petlenkov, Kristina Vassiljeva, Aleksei Tepljakov
Control of Magnetic Levitation System	B.Sc.	Juri Belikov, Eduard Petlenkov, Kristina Vassiljeva, Aleksei Tepljakov

Lõputööde teemad: www.a-lab.ee/edu/
14.10.2015. seisuga 54 teemat
+ edukalt kaitstud tööd



Control Lab
www.a-lab.ee



thnks

jurgo.preden@ttu.ee

Current projects

- **INformation INteroperability & INtelligence Interoperability by STatistics, Agents, Reasoning and Semantics IN-4-STARS (European Defence Agency)**
 - heterogeneous information fusion,
 - multi level security
 - semantic interoperability
- **Sensor, information processing, exchange and visualization methods for ISR applications (Estonian Ministry of Defence)**
- **Signal processing for ISR (US Army Research Laboratory)**